



















Self-similarity at various scales

Various types of fault rock, shown at increasing magnifications:

(a) shown in outcrop; (b) same as (a) in thin section; (c) thin section with angular (in-situ) fragments; (d) same as (c) with angular (in-situ) and rounded (dislocated) fragments; (e) SEM micrograph with (dislocated) angular fragments.







d



Figure 13.2

Fragmentation of a cube.

Fragmentation of the cube produces 8 cubes (F = 8) of I/2 the width of the original.

(a) Example of a cube where, at each scale, 2 out of 8 cubes remain unfragmented (N = 2), while 6 are fragmented further;

(b) front view of cube (a): the fragmentation fraction, f = (F - N) / F = 6 / 8;

(c) front view of a cube with f = 4 / 8;

(d) front view of a cube with f = I / 8.





Two conceptual models for grain size determination. (a) Stereological model: particles are diluted in matrix; (b) fractal model: fragments are densely packed.



Fractal dimension of grain size distribution created by fragmenting a cube.

Fragmentation number, F, is 8 (as in Figure 13.2), fragmentation fractions, f, range from 1/8 to 7/8.

(a) Log(N)-log(r) plot, where N = number and R = size of fragments, the slope, D_{3d} , is the fractal dimension of the size distribution of 3-D grains;

(b) log(N)-log(r) plot where N = number and r = size of cross sections of fragments, the slope, D_{2d}, is the fractal dimension of the size distribution of 2-D grains;

(c) log(V)-log(r) plot where V = volume and R = size of fragments, E = D_{3d} - 3.



a

b





С

Figure 13.5

Higher fragmentation numbers.

Front views of cubes with different fragmentation numbers, F, and different fragmentation fractions, f.

The cube is fragmented into:

(a) $F = 2 \cdot 2 \cdot 2 = 8$, N = 2, f = 6 / 8; (b) $F = 3 \cdot 3 \cdot 3 = 27$, N = 3, f = 24 / 27; (c) F = 4 + 4 = 64, N = 4, f = 60 / 64

(c) $F = 4 \cdot 4 \cdot 4 = 64$, N = 4, f = 60 / 64.



Fractal dimensions for different fragmentations.

Plots of fractal dimension, D_{3d}, versus number of crushed fragments, for different fragmentation numbers, F.



Fractal dimension for continuous fragmentation fraction, f.

Fragmentation number, F = 8.

(a) Discrete fragmentation fraction, $f = (F - N_i) / F$ for i = I to 8;

(b) same plot as (a) for continuously defined f : (0.00 \leq f \leq 1.00).



Fractal dimension for continuously defined fragmentation numbers and fragmentation fractions.

(a) D_{3d} for fragmentation numbers $F \ge 8$;

(b) D_{3d} for fragmentation numbers $F \leq 8$;

(c) D_{2d} for fragmentation numbers $F \ge 8$, note that $D_{2d} = D_{3d} - I$;

(d) D_{2d} for fragmentation numbers $F \leq 8$, note that $D_{2d} = D_{3d} - I$.

Plots (c) and (d) correspond to region framed in (a) and (b).



a

Figure 13.9

Fractal dimensions from different fragmentation processes.

Iso-lines of fractal dimension, D_{3d}, for varying fragmentation numbers, N, and fragmentation fractions, f.

(a) Curves of D_{3d} for (0% \leq f \leq 100%) and (0 \leq F \leq 125);

(b) expanded view of plot indicated by rectangle in (a) for (50% $\leq f \leq 100\%$) and (0 $\leq F \leq 8$).



b

23.7 % matrix

a

31.6 % matrix

42.2 % matrix

С

Figure 13.10

Concept of fragmentation matrix. Area fraction of fragmentation matrix is defined by matrix length scale, L_m ; $L_m = g / G$ where g = largest grain in matrix and G = largest grain present in image. (a) $L_m = I / 32$ and matrix content = 23.7 %; (b) $L_m = I / I6$ and matrix content = 31.6 %; (c) $L_m = I / 8$ and matrix content = 42.2 %. a







1/32

Figure 13.11

Apparent matrix content and fractal dimension.

(a) Cumulative volume, ΣV , is shown as function of log(R) for different D_{3d} (compare Figure 13.4.c); fragmentation

number F = 8, f = fragmentation fraction, R = size of fragments, $D_{3d} = fractal dimension of the size distribution of 3-D$ grains;

(b) matrix contents, m%, is shown as functions of D_{2d} for different matrix lengths scales, L_m ; the fractal dimension (0.00 \leq $D_{2d} \le 2.00$);

(c) matrix-D diagram showing fractal dimension ($0.00 \le D_{2d} \le 2.00$) versus matrix content for a range of matrix lengths scales, $L_m = 1/32$, 1/16, 1/8, 1/4 and 1/2 (for L_m see Figure 13.10).







Deriving the fractal dimension from the matrix content.

(a) SEM micrograph of fault rock at increasing magnification;

(b) bitmaps of (a), area percentage of matrix indicated;

(c) matrix-D diagram (see Figure 13.11) with matrix data for samples 1 to 5; matrix length scale, $L_m = 1/16$ for 1,2, $L_m = 1/8$ for 3,4, and $L_m > 1/4$ for 5;

(d) log(N)-log(R) plot constructed from D-values (slopes) of areas 1 to 5.





b

С

Figure 13.13

Local variation of the fractal dimension.

(a) SEM micrograph of experimentally produced cataclastic shear zone (displacement vertical, shear sense indicated, sample courtesy Nynke Keulen);

(b) bitmap of (a), 5 sites are indicated;

(c) matrix-D diagram (see Figure 13.11) with matrix data for sites 1 to 5; blue = data for entire bitmap; matrix length scale, $L_m = 1/8$ for entire image, $L_m = 1/4$ for areas 1 to 5.





a

b

Figure 13.14

Non-fractal size distribution.

- (a) Bitmap of experimentally produced cataclastic shear zone (Figure 13.13);
- (b) grain size analysis of fragmented part;
- (c) grain size analysis of part with mature gouge;
- r = size, N = number of fragments, total number indicated; D = negative slope of line fit.

cracked • gouge



b

Figure 13.15

Fractal dimension from measured matrix content and D-value from measured grain size analysis.

(a) Matrix contents as functions of D, expanded version of plot shown in Figure 13.11.b; black symbols are measured data points for cracked and gouge material;

(b) expanded matrix-D diagram (see Figure 13.11.c); same data points as in Figure 13.15.a; note D > 2 for gouge.

Lines denote matrix lengths scales $L_m = 1/32$, 1/16, 1/8, 1/4 and 1/2 (see Figure 13.11.c);

pink and gray shaded areas outline range of matrix%- and D- values separating cracked from gouge material.







C

С

b



Figure 13.16

Mapping fractal dimensions of grain size distributions.

(a) The Lazy D map menu;

(b) step I: creating matrix density maps: 63 · 63 Gauss filter kernel shown as brightness image;

(c) step II: converting to fractal dimension: look-up tables LUT1 to LUT5 for matrix length scales, L_m , from 1/2 to 1/32

(d) step III: using color LUTs to visualize (example from left to right: 10 colors for 0-100% matrix, 20 steps with red line at 50% and yellow strip at 80%).





С

Figure 13.17

Creating look-up tables from matrix-D diagrams.

Matrix density (0% to 100%) is converted to index (0 to 255), fractal dimension, D_{2d}, to gray value, GV, (0 to 255).

(a) and (c) for $(0.00 \le D_{2d} \le 2.00)$; matrix lengths scales, L_m, are indicated.

(b) and (d) for (1.00 \leq D_{2d} \leq 2.00); name of LUT indicated.





Preparing the bitmap.

Pre-processing by rolling ball background subtraction with decreasing radius, by enhancing, and bicubic smoothing (top to bottom).

(a) Grayscale images, radius of rolling ball indicated;

(b) histogram with threshold level indicated;

(c) resulting bitmap, average area fraction of matrix indicated; arrows point to areas where matrix is underestimated.



matrix = 65%

















Figure 13.19

Creating matrix density maps by Gauss convolution..

Matrix density images are calculated by de-magnifying image proportional to 63 · 63 Gauss filter kernel (maximum filter size for Image SXM), (2) convolving, and (3) re-magnifying to original size.

(a) Original bitmap, average gray value = 164, corresponding to matrix density of 65 %;

(b) to (e) matrix density images, the corresponding filter diameters are indicated; note that range in histograms decreases while average matrix density remains constant (65 %).



Visualizing matrix density maps.

(a) Scaled matrix density map, diameter of Gauss filter = 200 pixels;

(b) same as (a) seen with 20 gray levels, 50% and 65% contour are indicated in red and yellow, respectively;

(c) color coding of matrix content, lower cut-off = 10% (white), upper cut-off = 90% (black).





e

f

Converting matrix density to fractal dimension.

(a) Scaled map of fractal dimension (D map) obtained by applying LUT3 (for $L_m = 1/8$) to matrix density image (Gauss

- filter d = 200 pixels); average D_{2d} = 1.76; LUT shown in upper left corner;
- (b) same as (a) after stretching gray values to $(1.00 < D_{2d} < 2.00)$;
- (c) same as (a) after cropping to $D_{2d} < 1.8$;
- for comparison, (a) and (b) shown with 20 gray levels;
- (d) same as (a) using 'Fire-2' LUT of Image SXM and setting LUT options to 20 colors;

(e) same as (c), after applying command [E] of the Lazy D map macro a second time (1.50 \leq D_{2d} \leq 2.00), filling the white area with black, setting LUT options to 10 colors and applying LUT;

(f) contour map obtained from (e) using 'Find Edges' command (Process menu).



Two examples for D mapping. (a) SEM micrographs of experimentally produced fault at two different magnifications; (b) matrix density maps; size of Gauss filter is indicated by yellow circle; (c) color-coded matrix density maps; average matrix content is indicated; (d) D maps using LUT3 for a cut-off matrix grain size of $L_m = 1/8$; average fractal dimension, D_{2d} , of grain size distribution is indicated.



| %00 I

f



D map of natural fault rock.

(a) Thin section of natural fault rock taken from low angle detachment fault, F = trace of (horizontal) fault surface;
(b) bitmap of (a); average density indicated;

(c) matrix density map; histogram on right; size of Gauss filter indicated by yellow circle;

(d) matrix density profile of (c), averaged over image height;

(e) D map of (c) using LUT2 ($L_m = I/4$); color coding on right; average fractal dimension indicated;

(f) D profile of (e), averaged over image height; range of values ($1.60 \le D_{2d} \le 1.80$) is highlighted.